

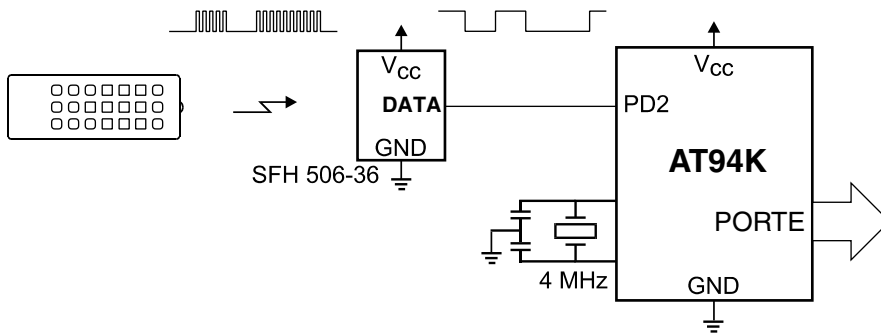


RC5 IR Remote Control Receiver

Features

- Low-cost
- Compact Design, Only One External Component
- Requires Only One Controller Pin, Any AT94K Device Can Be Used
- Size-efficient Code

Figure 1. RC5 Receiver



Introduction

Most audio and video systems are equipped with an infra-red remote control. This application note describes a receiver for the frequently used Phillips/Sony RC5 coding scheme.

The RC5 code is a 14-bit word bi-phase coded signal, see Figure 2. The first two bits are start bits, and their value equals to 1. The next bit is a control bit or toggle bit, which is inverted every time a button is pressed on the remote control transmitter. Five system bits hold the system address so that only the right system responds to the code. Usually, TV sets have the system address 0, VCRs the address 5 and so on. The command sequence is six bits long, allowing up to 64 different commands per address.

The bits are transmitted in bi-phase code, also known as Manchester code, see Figure 3. Figure 4 shows an example where the command 0x35 is sent to system 5.

Figure 2. RC5 Frame Format

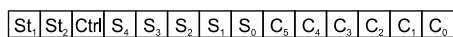


Figure 3. Bi-phase Coding

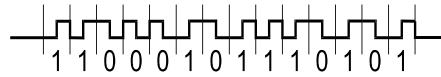


Programmable
SLI
AT94K
AT94S

Application
Note



Figure 4. Example of Transmission



Timing

The bit length is approximately 1.8 ms, and the code is repeated every 114 ms. To improve noise rejection, the pulses are modulated at 36 kHz. The easiest way to receive these pulses is to use an integrated IR-receiver/demodulator like the Siemens SFH 506-36. This is a 3-pin device that receives the infra-red burst and gives out the demodulated bit stream at the output pin. Note that the data is inverted compared to the transmitted data (i.e. the data is idle High).

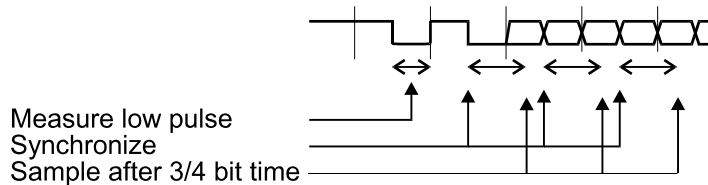
Software

The assembly code found in **2817.ASM** contains the RC5 decode routine. In addition, this file contains an example program which initializes the resources, decodes the RC5 data and outputs the received command on port D. This file can be obtained from the FPSLIC software section of the Atmel web site, at www.atmel.com.

Detect Subroutine

When the detect subroutine is called, it first waits for the data line to be idle High for more than 3.5 ms. Then, a start bit can be detected. The length of the low part of the first start bit is measured. If no start bit is detected within 131 ms, or if the low pulse is longer than 1.1 ms, the routine returns indicating no command was received.

Figure 5. Synchronizing and Sampling of the Data



The measurement of the start bit is used to calculate two reference times, ref1 and ref2, which are used when sampling the data line. The program uses the edge in the middle of every bit to synchronize the timing. 3/4 bit length after this edge, the line is sampled. This is in the middle of the first half of the next bit, see Figure 5. The state is stored and the routine waits for the middle edge. Then, the timer is synchronized again and everything is repeated for the following bits. If the synchronizing edge is not detected within 5/4 bit times from the previous synchronizing edge, this is detected as a fault and the routine terminates.

When all the bits are received, the command and system address are stored in the “command” and “system” registers. The control bit is stored in bit 6 of “command”.

Table 1. “Decode” Subroutine Performance Figures

Parameter	Value
Code Size	72 words
Execution Cycles	–
Register Usage	Low Registers Used: 3 High Registers Used: 6 Global Registers: 6 Pointers Used: None

Table 2. “Detect” Register Usage

Register	Internal	Output
R1	“inttemp” – Used by TIM0_OVF	–
R2	“ref1” – Holds Timing Information	–
R3	“ref2” – Holds Timing Information	–
R16	“temp” – Temporary Register	–
R17	“timerL” – Timing Register	–
R18	“timerH” – Timing Register	–
R19	–	“system” – The System Address
R20	–	“command” – The Received Command
R21	“bitcnt” – Counts the Bits Received	–

Timer/Counter 0 Overflow Interrupt Handler

The function of the timer interrupt is to generate a clock base for the timing required. The routine increments the “timerL” register every 64 μ s, and the “timerH” every 16,384 ms.

Table 3. “TIM0_OVF” Interrupt Handler Performance Figures

Parameter	Value
Code Size	7 words
Execution Cycles	6 + reti
Register Usage	Low Registers Used: 2 High Registers Used: 2 Global Registers: 0 Pointers Used: None

Table 4. “TIM0_OVF” Register Usage

Register	Internal	Output
R0	“S” – Temporary Storage of Sreg	–
R1	“inttemp” – Used by TIM0_OVF	–
R17	“timerL” – Incremented every 64 μ s	–
R18	“timerH” – Incremented every 16,384 ms	–

Example Program

The example program initializes the ports, sets up the timer and enables interrupts. Then, the program enters an eternal loop, calling the detect routine. If the system address is correct, the command is output on port B.

Table 5. Overall Performance Figures

Parameter	Value
Code Size	79 words - "detect" and "TIM0_OVF" 96 words - Complete Application Note
Register Usage	Low Registers: 4 High Registers: 6 Pointers: None
Interrupt Usage	Timer/Counter 0 Interrupt
Peripheral Usage	Timer/Counter Port D, pin 2 Port B (example program only)

Code

```

;*****
;* File Name           : "2817.asm"
;* Title              : RC5 IR Remote Control Decoder
;* Date               : 03.22.02
;* Version            : 1.0
;*
;* DESCRIPTION
;* This Application note describes how to decode the frequently used
;* RC5 IR remote control protocol.
;*
;* The timing is adapted for 4 MHz crystal
;*****
.include "AT94KDEF.INC"
.device AT94K

.equ   INPUT      =2           ;PD2
.equ   SYS_ADDR   =0           ;The system address

.def   S          =R0          ; Storage for the Status Register
.def   inttemp    =R1          ; Temporary variable for ISR
.def   ref1       =R2          ;
.def   ref2       =R3          ; Reference for timing

.def   temp       =R16         ; Temporary variable

.def   timerL     =R17         ; Timing variable updated every 14 us
.def   timerH     =R18         ; Timing variable updated every 16 ms
.def   system     =R19         ; Address data received
.def   command    =R20         ; Command received

.def   bitcnt     =R21         ; Counter

.cseg
.org 0
        rjmp      reset

```

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```
;*****
;* "TIM0_OVF" - Timer/counter overflow interrupt handler
;*
;* The overflow interrupt increments the "timerL" and "timerH"
;* every 64us and 16,384us.
;*
;* Crystal Frequency is 4 MHz
;* Number of words:7
;* Number of cycles:6 + reti
;* Low registers used:1
;* High registers used: 3
;* Pointers used:0
;*****
.org OVf0addr
TIM0_OVF:
    in     S,sreg                ; Store SREG
    inc   timerL                ; Updated every 64us
    inc   inttemp
    brne  TIM0_OVF_exit

    inc   timerH                ; if 256th int inc timer

TIM0_OVF_exit:
    out   sreg,S                ; Restore SREG
    reti

;*****
;* Example program
;*
;* Initializes timer, ports and interrupts.
;* Calls "detect" in an endless loop and puts the result out on
;* port E.
;*
;* Number of words:    16
;* Low registers used:  0
;* High registers used: 3
;* Pointers used:      0
;*****

reset:
    ldi   temp,low(RAMEND)      ;Initialize stackpointer for parts with
SW stack
    out   SPL,temp
    ldi   temp,high(RAMEND)
    out   SPH,temp

    ldi   temp,1                ;Timer/Counter 0 clocked at CK
    out   TCCR0,temp

    ldi   temp,1<<TOIE0        ;Enable Timer0 overflow interrupt
    out   TIMSK,temp

    ser   temp                  ;PORTE as output
```



```
out    DDRE,temp

sei                                ;Enable global interrupt

main:
rcall  detect                      ;Call RC5 detect routine

cpi    system,SYS_ADDR             ;Responds only at the specified address
brne   release

andi   command,0x3F               ;Remove control bit
out    PORTE,command

rjmp   main

release:
clr    command                    ;Clear PORTE
out    PORTE,command
rjmp   main

;*****
;* "detect" - RC5 decode routine
;*
;* This subroutine decodes the RC5 bit stream applied on PORTD
;* pin "INPUT".
;*
;* If success: The command and system address are
;* returned in "command" and "system".
;* Bit 6 of "command" holds the toggle bit.
;*
;* If failed: $FF in both "system" and "command"
;*
;* Crystal frequency is 4MHz
;*
;* Number of words:72
;* Low registers used: 3
;* High registers used: 6
;* Pointers used: 0
;*****
detect:
clr    inttemp                    ; Init Counters
clr    timerH

detect1:
clr    timerL

detect2:
cpi    timerH,8                   ;If line not idle within 131ms
brlo   d11
rjmp   fault                      ;then exit

d11:
cpi    timerL,55                  ;If line low for 3.5ms
```

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```
        brge     start1                ;then wait for start bit

        sbis    PIND,INPUT             ;If line is
        rjmp    detect1                ;low - jump to detect1
        rjmp    detect2                ;high - jump to detect2

start1:
        cpi     timerH,8               ;If no start bit detected
        brge    fault                 ;within 130ms then exit

        sbic    PIND,INPUT             ;Wait for start bit
        rjmp    start1

        clr     timerL                 ;Measure length of start bit

start2:
        cpi     timerL,17              ;If startbit longer than 1.1ms,
        brge    fault                 ;exit

        sbis    PIND,INPUT             ;
        rjmp    start2                ;Positive edge of 1st start bit

        mov     temp,timerL            ;timer is 1/2 bit time
        clr     timerL

        mov     ref1,temp
        lsr     ref1
        mov     ref2,ref1
        add     ref1,temp              ;ref1 = 3/4 bit time
        lsl     temp
        add     ref2,temp              ;ref2 = 5/4 bit time

start3:
        cp      timerL,ref1            ;If high period St2 > 3/4 bit time
        brge    fault                 ;exit

        sbic    PIND,INPUT             ;Wait for falling edge start bit 2
        rjmp    start3
        clr     timerL
        ldi     bitcnt,12              ;Receive 12 bits
        clr     command
        clr     system

sample:
        cp      timerL,ref1            ;Sample INPUT at 1/4 bit time
        brlo    sample

        sbic    PIND,INPUT             ;
        rjmp    bit_is_a_1            ;Jump if line high

bit_is_a_0:
        clc                                ;Store a '0'
        rol     command
        rol     system
```



```
                                ;Synchronize timing
bit_is_a_0a:
    cp        timerL,ref2        ;If no edge within 3/4 bit time
    brge     fault              ;exit
    sbis     PIND,INPUT          ;Wait for rising edge
    rjmp    bit_is_a_0a         ;in the middle of the bit

    clr     timerL
    rjmp    nextbit

bit_is_a_1:
    sec                                ;Store a '1'
    rol     command
    rol     system

                                ;Synchronize timing
bit_is_a_1a:
    cp        timerL,ref2        ;If no edge within 3/4 bit time
    brge     fault              ;exit
    sbic     PIND,INPUT          ;Wait for falling edge
    rjmp    bit_is_a_1a         ;in the middle of the bit

    clr     timerL

nextbit:
    dec     bitcnt                ;If bitcnt > 0
    brne     sample              ;get next bit
;All bits sucessfully received!
    mov     temp,command          ;Place system bits in "system"
    rol     temp
    rol     system
    rol     temp
    rol     system

    bst     system,5              ;Move toggle bit
    bld     command,6            ;to "command"

                                ;Clear remaining bits
    andi    command,0b01111111
    andi    system,0x1F

    ret

fault:
    ser     command              ;Both "command" and "system"
    ser     system              ;0xFF indicates failure
    ret
```




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